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Second-order conditions in $C^{1,1}$ constrained vector optimization

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Abstract

We consider the constrained vector optimization problem $\min_C f(x)$, $g(x) \in -K$, where $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$ are $C^{1,1}$ functions, and $C \subset \mathbb{R}^m$ and $K \subset \mathbb{R}^p$ are closed convex cones with nonempty interiors. Two type of solutions are important for our consideration, namely w -minimizers (weakly efficient points) and i -minimizers (isolated minimizers). We formulate and prove in terms of the Dini directional derivative second-order necessary conditions a point x^0 to be a w -minimizer and second-order sufficient conditions x^0 to be a i -minimizer of order two. We discuss the possible reversal of the sufficient conditions under suitable constraint qualifications of Kuhn-Tucker type. The obtained results improve the ones in Liu, Neittaanmäki, Křifek [20].

Key words: Vector optimization, $C^{1,1}$ optimization, Dini derivatives, Second-order conditions, Duality.

Math. Subject Classification: 90C29, 90C30, 90C46, 49J52.

1 Introduction

In this paper we deal with the constrained vector optimization problem

$$\min_C f(x), \quad g(x) \in -K, \quad (1)$$

where $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$ are given functions, and $C \subset \mathbb{R}^m$ and $K \subset \mathbb{R}^p$ are closed convex cones with nonempty interiors. Here n , m and p are positive integers. In the case when f and g are $C^{1,1}$ functions we derive second-order optimality conditions a point x^0 to be a solution of this problem. The paper is thought as a continuation of the investigation initiated by the authors in [7], where first-order conditions are derived in the case when f and g are $C^{0,1}$ functions. Recall that a function is said to be $C^{k,0}$ if it is k -times Fréchet differentiable with locally Lipschitz k -th derivative. The $C^{0,1}$ functions are the locally Lipschitz functions. The $C^{1,1}$ functions have been introduced in Hiriart-Urruty, Strodiot, Hien Nguen [13] and since then have found various application in optimization. In particular second-order conditions for $C^{1,1}$ scalar problems are studied in [13, 5, 16, 25, 26]. Second-order optimality conditions in vector optimization are investigated in [1, 4, 15, 21, 24], and what concerns $C^{1,1}$ vector optimization in [9, 10, 18, 19, 20]. The given in the present paper approach and results generalize that of [20].

The assumption that f and g are defined on the whole space \mathbb{R}^n is taken for convenience. Since we deal only with local solutions of problem (1), evidently our results generalize straightforward for functions f and g being defined on an open subset of \mathbb{R}^n . Usually the solutions of (1) are called points of efficiency. We prefer, like in the scalar optimization, to call them minimizers. In Section 2 we define different type of minimizers. Among them in our considerations an important role play the w -minimizers (weakly

efficient points) and the i -minimizers (isolated minimizers). When we say first or second-order conditions we mean as usually conditions expressed in suitable first or second-order derivatives of the given functions. Here we deal with the Dini directional derivatives. In Section 3 first-order Dini derivative is defined and after [7] first-order optimality conditions for $C^{0,1}$ functions are recalled. In Section 4 we define second-order Dini derivative and formulate and prove second-order optimality conditions for $C^{1,1}$ functions. We note that our results improve the ones obtained in Liu, Neittaanmäki, Křížek [20]. In Section 5 we discuss the possibility to revert the obtained sufficient conditions under suitable constraint qualifications.

2 Preliminaries

For the norm and the dual parity in the considered finite-dimensional spaces we write $\|\cdot\|$ and $\langle \cdot, \cdot \rangle$. From the context it should be clear to exactly which spaces these notations are applied.

For the cone $M \subset \mathbb{R}^k$ its positive polar cone M' is defined by $M' = \{\zeta \in \mathbb{R}^k \mid \langle \zeta, \phi \rangle \geq 0 \text{ for all } \phi \in M\}$. The cone M' is closed and convex. It is known that $M'' := (M')' = \text{cl co } M$, see Rockafellar [23, Theorem 14.1, page 121]. In particular for the closed convex cone M we have $M' = \{\zeta \in \mathbb{R}^k \mid \langle \zeta, \phi \rangle \geq 0 \text{ for all } \phi \in M\}$ and $M = M'' = \{\phi \in \mathbb{R}^k \mid \langle \zeta, \phi \rangle \geq 0 \text{ for all } \zeta \in M'\}$.

If $\phi \in -\text{cl conv } M$, then $\langle \zeta, \phi \rangle \leq 0$ for all $\zeta \in M'$. We set $M'[\phi] = \{\zeta \in M' \mid \langle \zeta, \phi \rangle = 0\}$. Then $M'[\phi]$ is a closed convex cone and $M'[\phi] \subset M'$. Consequently its positive polar cone $M[\phi] = (M'[\phi])'$ is a closed convex cone, $M \subset M[\phi]$ and its positive polar cone satisfies $(M[\phi])' = M'[\phi]$. In this paper we apply this notation for $M = K$ and $\phi = g(x^0)$. Then we deal with the cones $K'[g(x^0)]$ (we call this cone the index set of problem (1) at x^0) and $K[g(x^0)]$.

For the closed convex cone M' we apply in the sequel the notation $\Gamma_{M'} = \{\zeta \in M' \mid \|\zeta\| = 1\}$. The sets $\Gamma_{M'}$ is compact, since it is closed and bounded.

Now we recall the concept of the so called oriented distance from a point to a set, being applied to give a scalar characterization of some type of solutions of vector optimization problems. Given a set $A \subset \mathbb{R}^k$, then the distance from $y \in \mathbb{R}^k$ to A is $d(y, A) = \inf\{\|a - y\| \mid a \in A\}$. The oriented distance from y to A is defined by $D(y, A) = d(y, A) - d(y, \mathbb{R}^k \setminus A)$. The function D is introduced in Hiriart-Urruty [11, 12] and since then many authors show its usefulness in optimization. Ginchev, Hoffmann [8] apply the oriented distance to study approximation of set-valued functions by single-valued ones and in case of a convex set A show the representation $D(y, A) = \sup_{\|\xi\|=1} (\langle \xi, y \rangle - \sup_{a \in A} \langle \xi, a \rangle)$ (this formula resembles [23] the conjugate of the support function of A). From here, when $A = -C$ and C is a closed convex cone, taking into account

$$\sup_{a \in -C} \langle \xi, a \rangle = \begin{cases} 0 & , \quad \xi \in C', \\ +\infty & , \quad \xi \notin C', \end{cases}$$

we get easily $D(y, -C) = \sup_{\|\xi\|=1, \xi \in C'} \langle \xi, y \rangle$.

In terms of the distance function we have

$$K[g(x^0)] = \{w \in \mathbb{R}^p \mid \limsup_{t \rightarrow 0^+} \frac{1}{t} d(g(x^0) + tw, -C) = 0\},$$

that is $K[g(x^0)]$ is the contingent cone [3] of K at $g(x^0)$.

We call the solutions of problem (1) minimizers. The solutions are understood in a local sense. In any case a solution is a feasible point x^0 , that is a point satisfying the constraint $x^0 \in -K$.

The feasible point x^0 is said to be a w -minimizer (weakly efficient point) for (1) if there exists a neighbourhood U of x^0 , such that $f(x) \notin f(x^0) - \text{int } C$ for all $x \in U \cap g^{-1}(-K)$. The feasible point x^0 is said to be a e -minimizer (efficient point) for (1) if there exists a neighbourhood U of x^0 , such that

$f(x) \notin f(x^0) - (C \setminus \{0\})$ for all $x \in U \cap g^{-1}(-K)$. We say that the feasible point x^0 is a s -minimizer (strong minimizer) for (1) if there exists a neighbourhood U of x^0 , such that $f(x) \notin f(x^0) - C$ for all $x \in (U \setminus \{x^0\}) \cap g^{-1}(-K)$.

In [7] through the oriented distance the following characterization is derived. The feasible point x^0 is a w -minimizer (s -minimizer) for the vector problem (1) if and only if x^0 is a minimizer (strong minimizer) for the scalar problem

$$\min D(f(x) - f(x^0), -C), \quad g(x) \in -K. \quad (2)$$

Here we have an example of a scalarization of the vector optimization problem. By scalarization we mean a reduction of the vector problem to an equivalent scalar optimization problem.

We introduce another concept of optimality. We say that the feasible point x^0 is a i -minimizer (isolated minimizer) of order k , $k > 0$, for (1) if there exists a neighbourhood U of x^0 and a constant $A > 0$ such that $D(f(x) - f(x^0), -C) \geq A \|x - x^0\|^k$ for $x \in U \cap g^{-1}(-K)$.

In spite that the notion of isolated minimizer is defined through the norms, the following reasoning shows that in fact it is norm-independent. From the nonnegativeness of the right-hand side the definition of the i -minimizer of order k equivalently can be given by the inequality $d(f(x) - f(x^0), -C) \geq A \|x - x^0\|^k$ for $x \in U \cap g^{-1}(-K)$. Assume that another pair of norms in the original and image space denoted $\|\cdot\|$ is introduced. As it is known any two norms in a finite dimensional space over the reals are equivalent. Therefore there exist positive constants $\alpha_1, \alpha_2, \beta_1, \beta_2$, such that

$$\alpha_1 \|x\| \leq \|x\|_1 \leq \alpha_2 \|x\| \quad \text{for all } x \in X := \mathbb{R}^n,$$

$$\beta_1 \|y\| \leq \|y\|_1 \leq \beta_2 \|y\| \quad \text{for all } y \in Y := \mathbb{R}^m.$$

Denote by d^1 the distance associated to the norm $\|\cdot\|_1$. For $A \subset Y$ we have

$$d^1(y, A) = \sup\{\|y - a\|_1 \mid a \in A\} \geq \sup\{\beta_1 \|y - a\| \mid a \in A\} = \beta_1 d(y, A),$$

whence

$$\begin{aligned} d^1(f(x) - f(x^0), -C) &\geq \beta_1 d(f(x) - f(x^0), -C) \\ &\geq \beta_1 A \|x - x^0\|^k \geq \frac{\beta_1 A}{\alpha_2^k} \|x - x^0\|_1^k \quad \text{for } x \in U \cap g^{-1}(-K). \end{aligned}$$

Therefore, if x^0 is a i -minimizer of order k for (1) with respect to the pair of norms $\|\cdot\|$, it is also a i -minimizer with respect to the pair of norms $\|\cdot\|_1$, only the constant A should be changed to $(\beta_1 A)/\alpha_2^k$. Obviously, each i -minimizer is a s -minimizer. Further each s -minimizer is a e -minimizer and each e -minimizer is a w -minimizer (claiming this we assume that $C \neq \mathbb{R}^m$).

The concept of an isolated minimizer for scalar problems is introduced in Auslender [2]. For vector problems it has been extended in Ginchev [6], Ginchev, Guerraggio, Rocca [7], and under the name of strict minimizers in Jiménez [14] and Jiménez, Novo [15]. We prefer the name ‘‘isolated minimizer’’ given originally by A. Auslender.

3 First-order conditions

In this section after [7] we recall optimality conditions for problem (1) with $C^{0,1}$ data in terms of the first-order Dini directional derivative. The proofs can be found in [7].

Given a $C^{0,1}$ function $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^k$, we define the Dini directional derivative $\Phi'_u(x^0)$ of Φ at x^0 in direction $u \in \mathbb{R}^n$ as the set of the cluster points of $(1/t)(\Phi(x^0 + tu) - \Phi(x^0))$ as $t \rightarrow 0^+$, that is as the upper limit

$$\Phi'_u(x^0) = \text{Limsup}_{t \rightarrow 0^+} \frac{1}{t} (\Phi(x^0 + tu) - \Phi(x^0)).$$

If Φ is Fréchet differentiable at x^0 then the Dini derivative is a singleton, coincides with the usual directional derivative and can be expressed in terms of the Fréchet derivative $\Phi'(x^0)$ by $\Phi'_u(x^0) = \Phi'(x^0)u$. In connection with problem (1) we deal with the Dini derivative of the function $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^{m+p}$, $\Phi(x) = (f(x), g(x))$. Then we use the notation $\Phi'_u(x^0) = (f(x^0), g(x^0))'_u$. If at least one of the derivatives $f'_u(x^0)$ and $g'_u(x^0)$ is a singleton, then $(f(x^0), g(x^0))'_u = (f'_u(x^0), g'_u(x^0))$. Let us turn attention that always $(f(x^0), g(x^0))'_u \subset f'_u(x^0) \times g'_u(x^0)$, but in general these two sets do not coincide.

The following constraint qualification appears in the Sufficient Conditions part of Theorem 1.

$$\mathbb{Q}_{0,1}(x^0) : \quad \text{If } g(x^0) \in -K \text{ and } \frac{1}{t_k} (g(x^0 + t_k u^0) - g(x^0)) \rightarrow z^0 \in -K(x^0) \\ \text{then } \exists u^k \rightarrow u^0 : \exists k_0 \in \mathbb{N} : \forall k > k_0 : g(x^0 + t_k u^k) \in -K.$$

The constraint qualification $\mathbb{Q}_{0,1}(x^0)$ is of Kuhn-Tucker type. In 1951 Kuhn, Tucker [17] published the classical variant for differentiable functions and since then it is often cited in optimization theory.

Theorem 1 (First-order conditions) Consider problem (1) with f, g being $C^{0,1}$ functions and C and K closed convex cones.

(Necessary Conditions) Let x^0 be w -minimizer of problem (1). Then for each $u \in S$ the following condition is satisfied:

$$\mathbb{N}'_{0,1} : \quad \forall (y^0, z^0) \in (f(x^0), g(x^0))'_u : \exists (\xi^0, \eta^0) \in C' \times K' : \\ (\xi^0, \eta^0) \neq (0, 0), \quad \langle \eta^0, g(x^0) \rangle = 0 \quad \text{and} \quad \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle \geq 0.$$

(Sufficient Conditions) Let $x^0 \in \mathbb{R}^n$ and suppose that for each $u \in S$ the following condition is satisfied:

$$\mathbb{S}'_{0,1} : \quad \forall (y^0, z^0) \in (f(x^0), g(x^0))'_u : \exists (\xi^0, \eta^0) \in C' \times K' : \\ (\xi^0, \eta^0) \neq (0, 0), \quad \langle \eta^0, g(x^0) \rangle = 0 \quad \text{and} \quad \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle > 0.$$

Then x^0 is a i -minimizer of order one for problem (1).

Conversely, if x^0 is a i -minimizer of order one for problem (1) and the constraint qualification $\mathbb{Q}_{0,1}(x^0)$ holds, then condition $\mathbb{S}'_{0,1}$ is satisfied.

If g is Fréchet differentiable at x^0 , then instead of constraint qualification $\mathbb{Q}_{0,1}(x^0)$ we may consider the constraint qualification $\mathbb{Q}_1(x^0)$ given below.

$$\mathbb{Q}_1(x^0) : \quad \text{If } g(x^0) \in -K \text{ and } g'(x^0)u^0 = z^0 \in -K(x^0) \text{ then} \\ \text{there exists } \delta > 0 \text{ and a differentiable injective function} \\ \varphi : [0, \delta] \rightarrow -K \text{ such that } \varphi(0) = x^0 \text{ and } \varphi'(0) = g'(x^0)u^0.$$

In the case of a polyhedral cone K in $\mathbb{Q}_1(x^0)$ the requirement $\varphi : [0, \delta] \rightarrow -K$ can be replaced by $\varphi : [0, \delta] \rightarrow -K(x^0)$. This condition coincides with the classical Kuhn-Tucker constraint qualification (compare with Mangasarian [22, p. 102]).

The next theorem is a reformulation of Theorem 1 for C^1 problems, that is problems with f and g being C^1 functions.

Theorem 2 Consider problem (1) with f, g being C^1 functions and C and K closed convex cones.

(Necessary Conditions) Let x^0 be w -minimizer of problem (1). Then for each $u \in S$ the following condition is satisfied:

$$\mathbb{N}'_1 : \quad \exists (\xi^0, \eta^0) \in C' \times K' \setminus \{(0, 0)\} : \\ \langle \eta^0, g(x^0) \rangle = 0 \quad \text{and} \quad \langle \xi^0, f'(x^0)u \rangle + \langle \eta^0, g'(x^0)u \rangle \geq 0.$$

(Sufficient Conditions) Let $x^0 \in \mathbb{R}^n$.

Suppose that for each $u \in S$ the following condition is satisfied:

$$\mathbb{S}'_1 : \quad \begin{aligned} & \exists (\xi^0, \eta^0) \in C' \times K' \setminus \{(0, 0)\} : \\ & \langle \eta^0, g(x^0) \rangle = 0 \quad \text{and} \quad \langle \xi^0, f'(x^0)u \rangle + \langle \eta^0, g'(x^0)u \rangle > 0. \end{aligned}$$

Then x^0 is a i -minimizer of first order for problem (1).

Conversely, if x^0 is a i -minimizer of first order for problem (1) and let the constraint qualification $\mathbb{Q}_1(x^0)$ have place, then condition \mathbb{S}'_1 is satisfied.

The pairs of vectors (ξ^0, η^0) are usually referred to as the Lagrange multipliers. Here we have different Lagrange multipliers to different $u \in S$ (and different $(y^0, z^0) \in (f(x^0), g(x^0))'_u$). The natural question arises, whether a common pair (ξ^0, η^0) can be chosen to all directions. The next example shows that the answer is negative even for C^1 problems.

Example 1 Let $f : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $f(x_1, x_2) = (x_1, x_1^2 + x_2^2)$, and $g : \mathbb{R}^2 \rightarrow \mathbb{R}^2$, $g(x_1, x_2) = (x_1, x_2)$. Define $C = \{y \in (y_1, y_2) \in \mathbb{R}^2 \mid y_2 = 0\}$, $K = \mathbb{R}^2$. Then f and g are C^1 functions and the point $x^0 = (0, 0)$ is a w -minimizer of problem (1) (in fact x^0 is also a i -minimizer of order two, but not a i -minimizer of order one). At the same time the only pair $(\xi^0, \eta^0) \in C' \times K'$ for which $\langle \xi^0, f'(x^0)u \rangle + \langle \eta^0, g'(x^0)u \rangle \geq 0$ for all $u \in S$ is $\xi^0 = (0, 0)$ and $\eta^0 = (0, 0)$.

Theorem below 3 guarantees, that in the case of cones with nonempty interiors a nonzero pair (ξ^0, η^0) exists, which satisfies the Necessary Conditions of Theorem 1 and which is common for all directions. This is the reason why the second-order conditions in the next section are derived under the assumption of C and K closed convex cones with nonempty interior.

Theorem 3 (Necessary Conditions) Consider problem (1) with f, g being C^1 functions and C and K closed convex cones with nonempty interiors. Let x^0 be w -minimizer of problem (1). Then there exists a pair $(\xi^0, \eta^0) \in C' \times K' \setminus \{(0, 0)\}$ such that $\langle \eta^0, g(x^0) \rangle = 0$ and $\langle \xi^0, f'(x^0)u \rangle + \langle \eta^0, g'(x^0)u \rangle = 0$ for all $u \in \mathbb{R}^n$. The latter equality could be written also as $\langle \xi^0, f'(x^0) \rangle + \langle \eta^0, g'(x^0) \rangle = 0$.

4 Second-order conditions

In this section we derive optimality conditions for problem (1) with $C^{1,1}$ data in terms of the second-order Dini directional derivative.

Given a $C^{1,1}$ function $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^k$, we define the second-order Dini directional derivative $\Phi''_u(x^0)$ of Φ at x^0 in direction $u \in \mathbb{R}^n$ as the set of the cluster points of $(1/t^2)(\Phi(x^0 + tu) - \Phi(x^0) - \Phi'(x^0)u)$ as $t \rightarrow 0^+$, that is as the upper limit

$$\Phi''_u(x^0) = \text{Limsup}_{t \rightarrow 0^+} \frac{2}{t^2} (\Phi(x^0 + tu) - \Phi(x^0) - t\Phi'(x^0)u) .$$

If Φ is twice Fréchet differentiable at x^0 then the Dini derivative is a singleton and can be expressed in terms of the Hessian $\Phi''_u(x^0) = \Phi''(x^0)(u, u)$. In connection with problem (1) we deal with the Dini derivative of the function $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^{m+p}$, $\Phi(x) = (f(x), g(x))$. Then we use the notation $\Phi''_u(x^0) = (f(x^0), g(x^0))''_u$. Let us turn attention that always $(f(x^0), g(x^0))''_u \subset f''_u(x^0) \times g''_u(x^0)$, but in general these two sets do not coincide.

We need the following lemma.

Lemma 1 Let $\Phi : \mathbb{R}^n \rightarrow \mathbb{R}^k$ be a $C^{1,1}$ function and Φ' be Lipschitz with constant L on the ball $\{x \mid \|x - x^0\| \leq r\}$, where $x^0 \in \mathbb{R}^n$ and $r > 0$. Then, for $u, v \in \mathbb{R}^m$ and $0 < t < r / \max(\|u\|, \|v\|)$ we have

$$\left\| \frac{2}{t^2} (\Phi(x^0 + tv) - \Phi(x^0) - t\Phi'(x^0)v) - \frac{2}{t^2} (\Phi(x^0 + tu) - \Phi(x^0) - t\Phi'(x^0)u) \right\|$$

$$\leq L (\|u\| + \|v\|) \|v - u\|.$$

In particular, for $v = 0$ we get

$$\left\| \frac{2}{t^2} (\Phi(x^0 + tu) - \Phi(x^0) - t\Phi'(x^0)u) \right\| \leq L \|u\|^2.$$

Proof. For $0 < t < r / \max(\|u\|, \|v\|)$ we have

$$\begin{aligned} & \left\| \frac{2}{t^2} (\Phi(x^0 + tv) - \Phi(x^0) - t\Phi'(x^0)v) - \frac{2}{t^2} (\Phi(x^0 + tu) - \Phi(x^0) - t\Phi'(x^0)u) \right\| \\ &= \frac{2}{t^2} \left\| (\Phi(x^0 + tv) - \Phi(x^0 + tu)) - t\Phi'(x^0)(v - u) \right\| \\ &= \frac{2}{t} \left\| \int_0^1 (\Phi'(x^0 + tu + st(v - u)) - \Phi'(x^0)) (v - u) ds \right\| \\ &\leq 2L \int_0^1 \|(1 - s)u + sv\| ds \|v - u\| \\ &\leq 2L \int_0^1 ((1 - s)\|u\| + s\|v\|) ds \|v - u\| = L (\|u\| + \|v\|) \|v - u\|. \end{aligned}$$

□

The next theorem states second-order necessary conditions in primal form, that is in terms of directional derivatives.

Theorem 4 (Second-order necessary conditions, Primal form) Consider problem (1) with f, g being $C^{1,1}$ functions, and C and K closed convex cones. Let x^0 be a w -minimizer for (1). Then for each $u \in \mathbb{R}^n$ the following two conditions hold.

$$\begin{aligned} \mathbb{N}'_p : & \quad (f'(x^0)u, g'(x^0)u) \notin -(\text{int } C \times \text{int } K[g(x^0)]), \\ \mathbb{N}''_p : & \quad \text{if } (f'(x^0)u, g'(x^0)u) \in -(C \times K[g(x^0)] \setminus \text{int } C \times \text{int } K[g(x^0)]) \\ & \quad \text{and } (y^0, z^0) \in (f(x^0), g(x^0))''_u \text{ then it holds} \\ & \quad \text{conv} \{(y^0, z^0), \text{im } (f'(x^0), g'(x^0))\} \cap -(\text{int } C \times K[g(x^0)]) = \emptyset. \end{aligned}$$

Proof. Condition \mathbb{N}'_p . Assume in the contrary, that

$$f'(x^0)u = \lim_{t \rightarrow 0^+} \frac{1}{t} (f(x^0 + tu) - f(x^0)) \in -\text{int } C \quad \text{and} \quad (3)$$

$$g'(x^0)u = \lim_{t \rightarrow 0^+} \frac{1}{t} (g(x^0 + tu) - g(x^0)) \in -\text{int } K[g(x^0)]. \quad (4)$$

We show first that there exists $\delta > 0$ such that $x^0 + tu$ is feasible for $0 < t < \delta$. For each $\bar{\eta} \in \Gamma_{K'}$ there exists $\delta\bar{\eta}$ and a neighbourhood $V(\bar{\eta})$ of $\bar{\eta}$ such that $\langle \eta, g(x^0 + tu) \rangle < 0$ for $\eta \in V(\bar{\eta})$. To show this we consider the two possibilities. If $\bar{\eta} \in \Gamma_{K[g(x^0)]'}$ the claim follows from

$$\frac{1}{t} \langle \bar{\eta}, g(x^0 + tu) \rangle = \langle \bar{\eta}, \frac{1}{t} (g(x^0 + tu) - g(x^0)) \rangle \rightarrow \langle \bar{\eta}, z^0 \rangle < 0.$$

For $\bar{\eta} \in \Gamma_{K'} \setminus \Gamma_{K[g(x^0)]'}$ we have $\langle \bar{\eta}, g(x^0) \rangle$, whence from the continuity of g we get $\langle \eta, g(x^0 + tu) \rangle < 0$ for (η, t) sufficiently close to $(\bar{\eta}, 0)$. From the compactness of $\Gamma_{K'}$ it holds $\Gamma_{K'} \subset V(\bar{\eta}_1) \cup \dots \cup V(\bar{\eta}_k)$. Then $\langle \eta, g(x^0 + tu) \rangle < 0$ holds for all $\eta \in \Gamma_{K'}$ with $0 < t < \delta := \min_{1 \leq i \leq k} \delta(\bar{\eta}_i)$.

Now (3) gives that $f(x^0 + tu) - f(x^0) \in -\text{int } C$ for all sufficiently small t , which contradicts the assumption that x^0 is a w -minimizer for (1).

Condition \mathbb{N}_p'' . Assume in the contrary, that for some $u \neq 0$ condition \mathbb{N}_p'' (for $u = 0$ obviously \mathbb{N}_p'' is satisfied). Therefore we have $(f'(x^0)u, g'(x^0)u) \in -(C \times K[g(x^0)] \setminus \text{int } C \times \text{int } K[g(x^0)])$ and there exists $(y(u), z(u)) \in (f(x^0), g(x^0))_u''$ such that for some $\lambda \in (0, 1)$ and some $w \in \mathbb{R}^n$ it holds

$$(1 - \lambda)y(u) + \lambda f'(x^0)w \in -\text{int } C,$$

$$(1 - \lambda)z(u) + \lambda g'(x^0)w \in -\text{int } K[g(x^0)].$$

According to the definition of the Dini derivative there exists a sequence $t_k \rightarrow 0^+$, such that $\lim_k y^k(u) = y(u)$ and $\lim_k z^k(u) = z(u)$, where for $v \in \mathbb{R}^n$ we put

$$y^k(v) = \frac{2}{t_k^2} (f(x^0 + t_k v) - f(x^0) - t_k f'(x^0)v),$$

$$z^k(v) = \frac{2}{t_k^2} (g(x^0 + t_k v) - g(x^0) - t_k g'(x^0)v).$$

Let $v^k \rightarrow u$ and f and g be Lipschitz with constant L in a neighbourhood of x^0 . For k "large enough" we have, as in Lemma 1,

$$\|y^k(v^k) - y^k(u)\| \leq L(\|u\| + \|v^k\|)\|v^k - u\|,$$

$$\|z^k(v^k) - z^k(u)\| \leq L(\|u\| + \|v^k\|)\|v^k - u\|.$$

Now we have $y^k(v^k) \rightarrow y(u)$ and $z^k(v^k) \rightarrow z(u)$, which follows from the estimations

$$\|y^k(v^k) - y(u)\| \leq \|y^k(v^k) - y^k(u)\| + \|y^k(u) - y(u)\|$$

$$\leq L(\|u\| + \|v^k\|)\|v^k - u\| + \|y^k(u) - y(u)\|,$$

$$\|z^k(v^k) - z(u)\| \leq \|z^k(v^k) - z^k(u)\| + \|z^k(u) - z(u)\|$$

$$\leq L(\|u\| + \|v^k\|)\|v^k - u\| + \|z^k(u) - z(u)\|.$$

For $k = 1, 2, \dots$, let v^k be such that $w = \frac{2(1-\lambda)}{t_k \lambda} (v^k - u)$, i. e. $v^k = u + \frac{\lambda}{2(1-\lambda)} t_k w$ and hence, $v^k \rightarrow u$. For every k , we have

$$\begin{aligned} g(x^0 + t_k v^k) - g(x^0) &= t_k g'(x^0)u + t_k g'(x^0)(v^k - u) + \frac{1}{2} t_k^2 z(u) + o(t_k^2) \\ &= t_k g'(x^0)u + \frac{1}{2(1-\lambda)} t_k^2 \left((1-\lambda)z(u) + \frac{2(1-\lambda)}{t_k} g'(x^0)(v^k - u) \right) + o(t_k^2) \\ &= t_k g'(x^0)u + \frac{1}{2(1-\lambda)} t_k^2 \left((1-\lambda)z(u) + \lambda g'(x^0) \left(\frac{2(1-\lambda)}{t_k \lambda} (v^k - u) \right) \right) + o(t_k^2) \\ &= t_k g'(x^0)u + \frac{1}{2(1-\lambda)} t_k^2 ((1-\lambda)z(u) + \lambda g'(x^0)w) + o(t_k^2) \\ &\in -K[g(x^0)] - \text{int } K[g(x^0)] + o(t^2) \subset -\text{int } K[g(x^0)], \end{aligned}$$

the last inclusion is satisfied for k large enough. We get from here (repeating partially the reasoning from the proof of \mathbb{N}_p') that $g(x^0 + t_k v^k) \in -\text{int } K$ for all sufficiently large k . Passing to a subsequence, we may assume that all $x^0 + t_k v^k$ are feasible. The above chain of equalities and inclusions can be repeated substituting g , $z(u)$ and $K[g(x^0)]$ respectively by f , $y(u)$ and C . We obtain in such a way $f(x^0 + t_k v^k) - f(x^0) \subset -\text{int } C$, which contradicts to x^0 w -minimizer for (1). \square

Now we establish second-order necessary and sufficient optimality conditions in dual form. We assume as usual that $f : \mathbb{R}^n \rightarrow \mathbb{R}^m$ and $g : \mathbb{R}^n \rightarrow \mathbb{R}^p$ are $C^{1,1}$ functions and $C \subset \mathbb{R}^m$, $K \subset \mathbb{R}^p$ are closed convex cones. Then for $x^0 \in \mathbb{R}^n$ we put

$$\Delta(x^0) = \{(\xi, \eta) \in C' \times K' \mid (\xi, \eta) \neq 0, \langle \eta, g(x^0) \rangle = 0, \langle \xi, f'(x^0) \rangle + \langle \eta, g'(x^0) \rangle = 0\}.$$

Theorem 5 (Second-order conditions, Dual form) Consider problem (1) with f and g being $C^{1,1}$ functions, and C and K closed convex cones with nonempty interiors.

(Necessary Conditions) Let x^0 be a w -minimizer for (1). Then for each $u \in \mathbb{R}^n$ the following two conditions hold:

$$\mathbb{N}'_p : \quad (f'(x^0)u, g'(x^0)u) \notin -(\text{int } C \times \text{int } K[g(x^0)]),$$

$$\mathbb{N}''_d : \quad \begin{aligned} & \text{if } (f'(x^0)u, g'(x^0)u) \in -(C \times K[g(x^0)] \setminus \text{int } C \times \text{int } K[g(x^0)]) \\ & \text{then } \forall (y^0, z^0) \in (f(x^0), g(x^0))''_u : \exists (\xi^0, \eta^0) \in \Delta(x^0) : \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle \geq 0. \end{aligned}$$

(Sufficient Conditions) Let x^0 be a feasible point for problem (1). Suppose that for each $u \in \mathbb{R}^n \setminus \{0\}$ one of the following two conditions is satisfied:

$$\mathbb{S}'_p : \quad (f'(x^0)u, g'(x^0)u) \notin -(C \times K[g(x^0)]),$$

$$\mathbb{S}''_d : \quad \begin{aligned} & (f'(x^0)u, g'(x^0)u) \in -(C \times K[g(x^0)] \setminus \text{int } C \times \text{int } K[g(x^0)]) \\ & \text{and } \forall (y^0, z^0) \in (f(x^0), g(x^0))''_u : \exists (\xi^0, \eta^0) \in \Delta(x^0) : \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle > 0. \end{aligned}$$

Then x^0 is a i -minimizer of order two for problem (1).

Proof. Necessary Conditions. The necessity of condition \mathbb{N}'_p is proved in Theorem 4. To complete the proof we show that condition \mathbb{N}''_d implies \mathbb{N}''_d . Thus, we assume that the convex sets $F_+ = \text{conv} \{(y^0, z^0), \text{im}(f'(x^0), g'(x^0))\}$ and $F_- = (\text{int } C \times \text{int } K[g(x^0)])$ do not intersect. Since $K \subset K[g(x^0)]$ and both C and K have nonempty interior, we see that both F_+ and F_- are nonempty. According to the Separation Theorem there exists a pair $(\xi^0, \eta^0) \neq (0, 0)$ and a real number α , such that

$$\begin{aligned} \langle \xi^0, y \rangle + \langle \eta^0, z \rangle &\leq \alpha \quad \text{for all } (y, z) \in F_-, \\ \langle \xi^0, y \rangle + \langle \eta^0, z \rangle &\geq \alpha \quad \text{for all } (y, z) \in F_+. \end{aligned} \quad (5)$$

Since F_- is a cone and F_+ contains the cone $\text{im}(f'(x^0), g'(x^0))$, we get $\alpha = 0$. Since moreover, $\text{im}(f'(x^0), g'(x^0))$ is a linear space, we see that $\langle \xi^0, y \rangle + \langle \eta^0, z \rangle = 0$ for all $(\xi, \eta) \in \text{im}(f'(x^0), g'(x^0))$. The first line in (5) gives now $(\xi^0, \eta^0) \in C' \times K[g(x^0)]'$, that is $(\xi^0, \eta^0) \in \Delta(x^0)$. With regard to $(y^0, z^0) \in F_+$, the second line gives $\langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle \geq 0$.

Sufficient Conditions. We prove that if x^0 is not a i -minimizer of order two for (1), then there exists $u^0 \in \mathbb{R}^n$, $\|u^0\| = 1$, for which neither of the conditions \mathbb{S}'_p and \mathbb{S}''_d is satisfied.

Choose a monotone decreasing sequence $\varepsilon_k \rightarrow 0^+$. Since x^0 is not a i -minimizer of order two, there exist sequences $t_k \rightarrow 0^+$ and $u^k \in \mathbb{R}^n$, $\|u^k\| = 1$, such that $g(x^0 + t_k u^k) \in -K$ and

$$D(f(x^0 + t_k u^k) - f(x^0), -C) = \max_{\xi \in \Gamma_{C'}} \langle \xi, f(x^0 + t_k u^k) - f(x^0) \rangle < \varepsilon_k t_k^2. \quad (6)$$

Passing to a subsequence, we may assume $u^k \rightarrow u^0$. We may assume also $y^{0,k} \rightarrow y^0$, $z^{0,k} \rightarrow z^0$, where we have put

$$y^{0,k} = \frac{2}{t_k^2} (f(x^0 + t_k u^0) - f(x^0) - t_k f'(x^0)u^0),$$

$$y^k = \frac{2}{t_k^2} (f(x^0 + t_k u^k) - f(x^0) - t_k f'(x^0)u^k),$$

$$z^{0,k} = \frac{2}{t_k^2} (g(x^0 + t_k u^0) - g(x^0) - t_k g'(x^0)u^0),$$

$$z^k = \frac{2}{t_k^2} (g(x^0 + t_k u^k) - g(x^0) - t_k g'(x^0)u^k).$$

The possibility to choose convergent subsequence $y^{0,k} \rightarrow y^0, z^{0,k} \rightarrow z^0$, follows from the boundedness of the differential quotient proved in Lemma 1. Now we have $(y^0, z^0) \in (f(x^0), g(x^0))'_u$. We may assume also that $0 < t_k < r$ and both f and g are Lipschitz with constant L on $\{x \mid \|x - x^0\| \leq r\}$. Now we have $z^k \rightarrow z^0$ which follows from the estimations obtained on the base of Lemma 1

$$\begin{aligned} \|z^k - z^0\| &\leq \|z^k - z^{0,k}\| + \|z^{0,k} - z^0\| \\ &\leq L(\|u^k\| + \|u^0\|) \|u^k - u^0\| + \|z^{0,k} - z^0\|. \end{aligned}$$

Similar estimations for y^k show that $y^k \rightarrow y^0$.

We prove that \mathbb{S}'_p is not satisfied at u^0 . For this purpose we must prove that

$$f'(x^0)u \in -C, \quad g'(x^0)u \in -K[g(x^0)].$$

Let $\varepsilon > 0$. We claim that there exists k_0 such that for all $\xi \in \Gamma_{C'}$ and all $k > k_0$ the following inequalities hold:

$$\langle \xi, \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) \rangle < \frac{1}{3} \varepsilon, \quad (7)$$

$$\langle \xi, f'(x^0)u^k - \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) \rangle < \frac{1}{3} \varepsilon, \quad (8)$$

$$\langle \xi, f'(x^0)(u^0 - u^k) \rangle < \frac{1}{3} \varepsilon. \quad (9)$$

Inequality (7) follows from (6). Inequality (8) follows from the Fréchet differentiability of f

$$\begin{aligned} &\langle \xi, f'(x^0)u^k - \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) \rangle \\ &\leq \left\| \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) - f'(x^0)u^k \right\| < \frac{1}{3} \varepsilon, \end{aligned}$$

which is true for all sufficiently small t_k . Inequality (9) follows from

$$\langle \xi, f'(x^0)(u^0 - u^k) \rangle \leq \|f'(x^0)\| \|u^0 - u^k\| < \frac{1}{3} \varepsilon,$$

which is true for $\|u^k - u^0\|$ “small enough”. Now we see, that for arbitrary $\xi \in \Gamma_{C'}$ and $k > k_0$ we have

$$\begin{aligned} \langle \xi, f'(x^0)u^0 \rangle &= \langle \xi, \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) \rangle \\ &+ \langle \xi, f'(x^0)u^k - \frac{1}{t_k} (f(x^0 + t_k u^k) - f(x^0)) \rangle \\ &+ \langle \xi, f'(x^0)(u^0 - u^k) \rangle < \frac{1}{3} \varepsilon + \frac{1}{3} \varepsilon + \frac{1}{3} \varepsilon = \varepsilon, \end{aligned}$$

and $D(f'(x^0)u^0, -C) = \max_{\xi \in \Gamma} \langle \xi, f'(x^0)u^0 \rangle < \varepsilon$. Since $\varepsilon > 0$ is arbitrary, we see $D(f'(x^0)u^0, -C) \leq 0$, whence $f'(x^0)u^0 \in -C$.

Similar estimations can be repeated with f and $\xi \in \Gamma_{C'}$ substituted respectively by g and $\eta \in K[g(x^0)]'$, whence we get $g'(x^0)u^0 \in -K[g(x^0)]$. The only difference occurs with the estimation (7). Then we have

$$\langle \eta, \frac{1}{t_k} (g(x^0 + t_k u^k) - g(x^0)) \rangle = \frac{1}{t_k} \langle \eta, g(x^0 + t_k u^k) \rangle \leq 0,$$

since $g(x^0 + t_k u^k) \in -K \subset -K[g(x^0)]$.

Now we prove that \mathbb{S}_d'' is not satisfied at x^0 . We assume that

$$(f'(x^0)u, g'(x^0)u) \in -(C \times K[g(x^0)]) \setminus \text{int } C \times \text{int } K[g(x^0)],$$

since otherwise the first assertion in condition \mathbb{S}_d'' would not be satisfied. It is obvious, that to complete the proof we must show that

$$\forall (\xi^0, \eta^0) \in \Delta(x^0) : \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle \leq 0.$$

Obviously, it is enough to show this inequality for $(\xi^0, \eta^0) \in \Delta(x^0)$ such that $\max(\|\xi^0\|, \|\eta^0\|) = 1$. Then

$$\begin{aligned} \langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle &= \lim_k \left(\langle \xi^0, y^k \rangle + \langle \eta^0, z^k \rangle \right) \\ &= \lim_k \left(\frac{2}{t_k^2} \langle \xi^0, f(x^0 + t_k u^k) - f(x^0) \rangle + \frac{2}{t_k^2} \langle \eta^0, g(x^0 + t_k u^k) - g(x^0) \rangle \right. \\ &\quad \left. - \frac{2}{t_k^2} \left(\langle \xi^0, f'(x^0)u^k \rangle + \langle \eta^0, g'(x^0)u^k \rangle \leq 0 \right) \right) \\ &\leq \limsup_k \frac{2}{t_k^2} D(f(x^0 + t_k u^k) - f(x^0), -C) + \limsup_k \frac{2}{t_k^2} \langle \eta^0, g(x^0 + t_k u^k) \rangle \\ &\leq \limsup_k \frac{2}{t_k^2} \varepsilon_k t_k^2 = 0. \end{aligned}$$

□

In fact, in Theorem 5 only conditions \mathbb{N}_d'' and \mathbb{S}_d'' are given in a dual form. Because of convenience for the proof conditions \mathbb{N}_p' and \mathbb{S}_p' are given in the same primal form as they appear in Theorem 4. However these conditions can be represented in a dual form too. For instance condition \mathbb{N}_p' can be written in the equivalent dual form

$$\exists (\xi, \eta) \in (C' \times K[g(x^0)]') : \langle \xi, f'(x^0)u \rangle + \langle \eta, g'(x^0)u \rangle > 0.$$

Theorems 3.1 and 4.2 in Liu, Neittaanmäki, Křížek [20] are of the same type as Theorem 5. The latter is however more general in the following aspects. Theorem 5 in opposite to [20] concerns arbitrary and not only polyhedral cones C . In Theorem 5 the conclusion in the sufficient conditions part is that x^0 is a i -minimizer of order two, while in [20] the weaker conclusion is proved, namely that the reference point is only ε -minimizer.

5 Reversal of the sufficient conditions

The isolated minimizers as more qualified notion of efficiency should be more essential solutions for the vector optimization problem than the ε -minimizers. As a result of using i -minimizers, we have seen in Theorem 1 that under suitable constraint qualifications the sufficient conditions admit reversal. Now we discuss the similar possibility to revert the sufficient conditions part of Theorem 5 under suitable second-order constraint qualifications of Kuhn-Tucker type. Unfortunately, the second-order case is more complicated than the first-order one. The proposed second-order constraint qualifications called $\mathbb{Q}_{1,1}(x^0)$ look more complicated than the first-order ones applied in Theorem 1. In spite of this, we succeeded in proving that conditions from the sufficient part of Theorem 5 are satisfied under the stronger hypothesis that x^0 is a i -minimizer of order two for the following constrained problem

$$\min_{\hat{C}} f(x), \quad g(x) \in -K, \quad \text{where } \hat{C} = \text{conv}(C, \text{im } f'(x^0)). \quad (10)$$

Obviously, each i -minimizer of order two for (10) is also a i -minimizer of order two for (1). It remains the open question, whether under the hypotheses that x^0 is a i -minimizer of order two for (1) the conclusion of Theorem 6 remains true.

In the sequel we consider the constraint qualification.

$\mathbb{Q}_{1,1}(x^0)$: The following conditions are satisfied:

- 1⁰. $g(x^0) \in -K$,
- 2⁰. $g'(x^0)u^0 \in -(K[g(x^0)] \setminus \text{int } K[g(x^0)])$,
- 3⁰. $\frac{2}{t_k^2} (g(x^0 + t_k u^0) - g(x^0) - t_k g'(x^0)u^0) \rightarrow z^0$,
- 4⁰. $(\forall \eta \in K[g(x^0)]', (\forall z \in \text{im } g'(x^0) : \langle \eta, z \rangle = 0) : \langle \eta, z^0 \rangle \leq 0)$ implies $\exists u^k \rightarrow u^0 : \exists k_0 \in \mathbb{N} : \forall k > k_0 : g(x^0 + t_k u^k) \in -K$.

Theorem 6 (Reversal of the second-order sufficient conditions) *Let x^0 be a i -minimizer of order two for the constrained problem (10) and suppose that the constraint qualification $\mathbb{Q}_{1,1}(x^0)$ holds. Then one of the conditions \mathbb{S}'_p or \mathbb{S}''_d from Theorem 5 is satisfied.*

Proof. Let x^0 be a i -minimizer of order two for problem (10), which means that $g(x^0) \in -K$ and there exists $r > 0$ and $A > 0$ such that $g(x) \in -K$ and $\|x - x^0\| \leq r$ implies

$$D(f(x) - f(x^0), -\hat{C}) = \max_{\xi \in \Gamma_{\hat{C}'}} \langle \xi, f(x) - f(x^0) \rangle \geq A \|x - x^0\|^2. \quad (11)$$

The point x^0 being a i -minimizer of order two for problem (10) is also a w -minimizer for (10) and hence also for (1). Therefore it satisfies condition \mathbb{N}'_p . Now it becomes obvious, that for each $u = u^0$ one and only one of the first-order conditions in \mathbb{S}'_p and the first part of \mathbb{S}''_d is satisfied. Suppose that \mathbb{S}'_p is not satisfied. Then the first part of condition \mathbb{S}''_d holds, that is

$$(f'(x^0)u^0, g'(x^0)u^0) \in -(C \times K[g(x^0)] \setminus \text{int } C \times \text{int } K[g(x^0)]).$$

We prove, that also the second part of condition \mathbb{S}''_d holds.

One of the following two cases may arise:

1⁰. *There exists $\eta^0 \in K[g(x^0)]'$ such that $\langle \eta^0, z \rangle = 0$ for all $z \in \text{im } f'(x^0)$ and $\langle \eta^0, z^0 \rangle > 0$.*

We put now $\xi^0 = 0$. Then we have obviously $(\xi^0, \eta^0) \in C' \times K[g(x^0)]'$ and $\langle \xi^0, f'(x^0) \rangle + \langle \eta^0, g'(x^0) \rangle = 0$. Thus $(\xi^0, \eta^0) \in \Delta(x^0)$ and $\langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle > 0$. Therefore condition \mathbb{S}''_d is satisfied.

2⁰. *For all $\eta \in K[g(x^0)]'$, such that $\langle \eta, z \rangle = 0$ for all $z \in \text{im } f'(x^0)$, it holds $\langle \eta, z^0 \rangle \leq 0$.*

This condition coincides with condition 4⁰ in the constraint qualification $\mathbb{Q}_{1,1}(x^0)$. Now we see that all points 1⁰–4⁰ in the constraint qualification $\mathbb{Q}_{1,1}(x^0)$ are satisfied. Therefore there exists $u^k \rightarrow u^0$ and a positive integer k_0 such that for all $k > k_0$ it holds $g(x^0 + t_k u^k) \in -K$. Passing to a subsequence, we may assume that this inclusion holds for all k . From (11) it follows that there exists $\xi^k \in \Gamma_{\hat{C}'}$ such that

$$D(f(x^0 + t_k u^k) - f(x^0), -\hat{C}) = \langle \xi^k, f(x^0 + t_k u^k) - f(x^0) \rangle \geq A t_k^2 \|u^k\|^2.$$

Passing to a subsequence, we may assume that $\xi^k \rightarrow \xi^0 \in \Gamma_{\hat{C}'}$. Let us underline that each $\xi \in \hat{C}'$ satisfies $\langle \xi, f'(x^0) \rangle = 0$. This follows from $\langle \xi, z \rangle \leq 0$ for all $z \in \text{im } f'(x^0)$ and the fact that $\text{im } f'(x^0)$ is a linear space. Now we have

$$\begin{aligned} & \langle \xi^k, \frac{2}{t_k^2} (f(x^0 + t_k u^k) - f(x^0) - t_k f'(x^0)u^k) \rangle \\ & \frac{2}{t_k^2} \langle \xi^k, (f(x^0 + t_k u^k) - f(x^0)) \rangle \geq \frac{2}{t_k^2} A t_k^2 \|u^k\|^2 = A \|u^k\|^2. \end{aligned}$$

Passing to a limit gives $\langle \xi^0, y^0 \rangle \geq 2A \|u^0\|^2 = 2A$. Putting $\eta^0 = 0$, we have obviously $(\xi^0, \eta^0) \in \Delta(x^0)$ and $\langle \xi^0, y^0 \rangle + \langle \eta^0, z^0 \rangle > 0$. \square

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